
BALANCED GROWTH PATH IN LABOR SEARCH AND MATCHING MODEL

JANUARY 9, 2017

CALIBRATION – PHILOSOPHY

- ❑ An economic model is a measuring device
- ❑ If model makes “believable” predictions along some important dimensions (i.e., “matches some key data”)...
- ❑ ...then maybe its predictions are “believable” along the novel dimensions of the model
- ❑ Getting some “partial derivatives” of the model in known directions correct...
- ❑ ...may build credibility that its “partial derivatives” in novel directions are at least not grossly incorrect
- ❑ Make model match some data of interest – often long-run (i.e., time-averaged data) growth facts
 - ❑ Preferably well-accepted “stylized facts”
 - ❑ Solow growth model in the background
 - ❑ Natural candidate: Kaldor growth facts
- ❑ Calibration vs. Estimation

CALIBRATION OF BASELINE RBC MODEL

- ❑ Must take a stand on three (related) points
 - ❑ Which data do we want model to match? (even constructing data is challenging...)
 - ❑ Functional forms (utility, production)
 - ❑ Parameter values

- ❑ Choose functional forms consistent with **“Kaldor-plus facts”**
 - ❑ **(K1)** Capital income share and labor income share of GDP are stationary
 - ❑ **(K2)** All real quantity variables grow at same rate in the long run (**“great ratios”**)
 - ❑ **(K3)** Real interest rate is stationary
 - ❑ **(K4)** Hours per worker are stationary
 - ❑ **(K5)** (K2) requires trend productivity to be labor-augmenting (Phelps 1966)

CALIBRATION OF BASELINE RBC MODEL

- ❑ Must take a stand on three (related) points
 - ❑ Which data do we want model to match? (even constructing data is challenging...)
 - ❑ Functional forms (utility, production)
 - ❑ Parameter values

- ❑ Choose functional forms consistent with **“Kaldor-plus facts”**
 - ❑ **(K1)** Capital income share and labor income share of GDP are stationary
 - ❑ **(K2)** All real quantity variables grow at same rate in the long run (**“great ratios”**)
 - ❑ **(K3)** Real interest rate is stationary
 - ❑ **(K4)** Hours per worker are stationary
 - ❑ **(K5)** (K2) requires trend productivity to be labor-augmenting (Phelps 1966)

- ❑ Often start with RBC model that abstracts from long-run growth

- ❑ **But “true” calibration begins with model featuring only long-run growth**
 - ❑ Puts restrictions on instantaneous utility and production forms
 - ❑ Use **(K1)-(K5)** to obtain these restrictions

CALIBRATION OF BASELINE RBC MODEL

- ❑ Must take a stand on three (related) points
 - ❑ Which data do we want model to match? (even constructing data is challenging...)
 - ❑ Functional forms (utility, production)
 - ❑ Parameter values

- ❑ Choose functional forms consistent with **“Kaldor-plus facts”**
 - ❑ **(K1)** Capital income share and labor income share of GDP are stationary
 - ❑ **(K2)** All real quantity variables grow at same rate in the long run (**“great ratios”**)
 - ❑ **(K3)** Real interest rate is stationary
 - ❑ **(K4)** Hours per worker are stationary
 - ❑ **(K5)** (K2) requires trend productivity to be labor-augmenting (Phelps 1966)

- ❑ Often start with RBC model that abstracts from long-run growth

- ❑ **But “true” calibration begins with model featuring only long-run growth**
 - ❑ Puts restrictions on instantaneous utility and production forms
 - ❑ Use **(K1)-(K5)** to obtain these restrictions

- ❑ Richer models: more calibration targets and/or treating data differently
 - ❑ Monopoly markups (e.g., Dixit-Stiglitz and sticky price models)
 - ❑ Probability of finding a job (e.g., labor matching models)
 - ❑ Durable consumption vs. non-durable consumption

SEARCH MODEL WITH GROWTH

- Absent shocks, TFP grows at deterministic rate γ

- Planner problem/perfect competition

$$\max E_0 \sum_{t=0}^{\infty} \beta^t u(C_t, lfp_t) \quad \text{subject to}$$

$$C_t + K_{t+1} - (1 - \delta)K_t + \Omega_t \cdot v_t = z_t F(K_t, n_t X_t)$$

Trend productivity is labor-augmenting (Harrod-neutral) (Makes use of fact **(K5)**)

Flow resource constraint

Aggregate LOM of labor

Evolution of deterministic component of productivity

Red indicates variables or parameters that will be modified when detrending the model

$$n_t = (1 - \rho)n_{t-1} + m(lfp_t - (1 - \rho)n_{t-1}, v_t)$$

$$X_{t+1} = \gamma X_t, \quad \gamma \geq 1$$

given stochastic process for evolution of z_t and $(K_{-1}, n_{-1}, z_0, X_0)$

SEARCH MODEL WITH GROWTH

- Absent shocks, TFP grows at deterministic rate γ

- Planner problem/perfect competition

$$\max E_0 \sum_{t=0}^{\infty} \beta^t u(C_t, lfp_t) \quad \text{subject to}$$

$$C_t + K_{t+1} - (1 - \delta)K_t + \Omega_t \cdot v_t = z_t F(K_t, n_t X_t)$$

Trend productivity is labor-augmenting (Harrod-neutral) (Makes use of fact **(K5)**)

Flow resource constraint

Aggregate LOM of labor

Evolution of deterministic component of productivity

Red indicates variables or parameters that will be modified when detrending the model

$$n_t = (1 - \rho)n_{t-1} + m(lfp_t - (1 - \rho)n_{t-1}, v_t)$$

$$X_{t+1} = \gamma_t X_t, \quad \gamma \geq 1$$

given stochastic process for evolution of z_t and $(K_{-1}, n_{-1}, z_0, X_0)$

- Suppose $z_t = 1$ always, so only deterministic growth
- Deterministic dynamics of $(C_t, K_{t+1}, lfp_t, n_t, v_t, X_t)$ governed by

(1)	$\frac{u_{lfp}(C_t, lfp_t)}{u_c(C_t, lfp_t)} = \Omega_t \cdot \frac{m_s(s_t, v_t)}{m_v(s_t, v_t)}$	Labor supply function	$\frac{\Omega_t}{m_v(s_t, v_t)} = X_t F_2(K_t, n_t X_t)$	Labor demand function
(2)	$\frac{u_c(C_t, lfp_t)}{bu_c(C_{t+1}, lfp_{t+1})} = F_1(K_{t+1}, n_{t+1} X_{t+1}) + 1 - \delta$	Capital supply function	(3)	$+ (1 - \rho) \left(\frac{bu_c(C_{t+1}, lfp_{t+1})}{u_c(C_t, lfp_t)} \right) \cdot \frac{\Omega_{t+1} (1 - m_s(s_{t+1}, v_{t+1}))}{m_v(s_{t+1}, v_{t+1})}$
(4)	$C_t + K_{t+1} - (1 - \delta)K_t + \Omega_t \cdot v_t = F(K_t, n_t X_t)$			
(6)	$X_{t+1} = \gamma_t X_t$	Normalize $X_0 = 1$	(5)	$n_t = (1 - \rho)n_{t-1} + m(s_t, v_t)$ LOM of labor

RESTRICTIONS ON FUNCTIONAL FORMS

□ Deterministic dynamics of $(C_t, K_{t+1}, lfp_t, n_t, v_t, X_t)$ governed by

$$(1) \quad -\frac{u_{lfp}(C_t, lfp_t)}{u_C(C_t, lfp_t)} = \Omega_t \cdot \frac{m_s(s_t, v_t)}{m_v(s_t, v_t)}$$

$$(3) \quad \frac{\Omega_t}{m_v(s_t, v_t)} = X_t F_2(K_t, n_t X_t)$$

$$(2) \quad \frac{u_C(C_t, lfp_t)}{bu_C(C_{t+1}, lfp_{t+1})} = F_1(K_{t+1}, n_{t+1} X_{t+1}) + 1 - \delta$$

$$+ (1 - \rho) \left(\frac{bu_C(C_{t+1}, lfp_{t+1})}{u_C(C_t, lfp_t)} \right) \cdot \frac{\Omega_{t+1} (1 - m_s(s_{t+1}, v_{t+1}))}{m_v(s_{t+1}, v_{t+1})}$$

$$(4) \quad C_t + K_{t+1} - (1 - \delta)K_t + \Omega_t \cdot v_t = F(K_t, n_t X_t)$$

$$(5) \quad n_t = (1 - \rho)n_{t-1} + m(s_t, v_t)$$

$$(6) \quad X_{t+1} = \gamma_t X_t$$

RESTRICTIONS ON FUNCTIONAL FORMS

□ Deterministic dynamics of $(C_t, K_{t+1}, lfp_t, n_t, v_t, X_t)$ governed by

$$\begin{aligned}
 (1) \quad & -\frac{u_{lfp}(C_t, lfp_t)}{u_C(C_t, lfp_t)} = \Omega_t \cdot \frac{m_s(s_t, v_t)}{m_v(s_t, v_t)} & (3) \quad & \frac{\Omega_t}{m_v(s_t, v_t)} = X_t F_2(K_t, n_t X_t) \\
 (2) \quad & \frac{u_C(C_t, lfp_t)}{bu_C(C_{t+1}, lfp_{t+1})} = F_1(K_{t+1}, n_{t+1} X_{t+1}) + 1 - \delta & & + (1 - \rho) \left(\frac{bu_C(C_{t+1}, lfp_{t+1})}{u_C(C_t, lfp_t)} \right) \cdot \frac{\Omega_{t+1} (1 - m_s(s_{t+1}, v_{t+1}))}{m_v(s_{t+1}, v_{t+1})} \\
 (4) \quad & C_t + K_{t+1} - (1 - \delta)K_t + \Omega_t \cdot v_t = F(K_t, n_t X_t) & (5) \quad & n_t = (1 - \rho)n_{t-1} + m(s_t, v_t) & (6) \quad & X_{t+1} = \gamma_t X_t
 \end{aligned}$$

□ **(K1) Capital income share and labor income share of GDP are stationary**
And viewing economic profits as zero

$$\Rightarrow F(K, nX) = K^\alpha (nX)^{1-\alpha} \quad (\alpha \approx 0.4)$$

RESTRICTIONS ON FUNCTIONAL FORMS

□ Deterministic dynamics of $(C_t, K_{t+1}, lfp_t, n_t, v_t, X_t)$ governed by

$$(1) \quad -\frac{u_{lfp}(C_t, lfp_t)}{u_C(C_t, lfp_t)} = \Omega_t \cdot \frac{m_s(s_t, v_t)}{m_v(s_t, v_t)}$$

$$(3) \quad \frac{\Omega_t}{m_v(s_t, v_t)} = X_t F_2(K_t, n_t X_t)$$

$$(2) \quad \frac{u_C(C_t, lfp_t)}{bu_C(C_{t+1}, lfp_{t+1})} = \alpha \left(\frac{K_{t+1} / X_{t+1}}{n_{t+1}} \right)^{\alpha-1} + 1 - \delta$$

$$+ (1 - \rho) \left(\frac{bu_C(C_{t+1}, lfp_{t+1})}{u_C(C_t, lfp_t)} \right) \cdot \frac{\Omega_{t+1} (1 - m_s(s_{t+1}, v_{t+1}))}{m_v(s_{t+1}, v_{t+1})}$$

$$(4) \quad C_t + K_{t+1} - (1 - \delta)K_t + \Omega_t \cdot v_t = K_t^\alpha (n_t X_t)^{1-\alpha}$$

$$(5) \quad n_t = (1 - \rho)n_{t-1} + m(s_t, v_t)$$

$$(6) \quad X_{t+1} = \gamma_t X_t$$

RESTRICTIONS ON FUNCTIONAL FORMS

□ Deterministic dynamics of $(C_t, K_{t+1}, lfp_t, n_t, v_t, X_t)$ governed by

$$\begin{aligned}
 (1) \quad & -\frac{u_{lfp}(C_t, lfp_t)}{u_C(C_t, lfp_t)} = \Omega_t \cdot \frac{m_s(s_t, v_t)}{m_v(s_t, v_t)} & (3) \quad & \frac{\Omega_t}{m_v(s_t, v_t)} = X_t F_2(K_t, n_t X_t) \\
 (2) \quad & \frac{u_C(C_t, lfp_t)}{bu_C(C_{t+1}, lfp_{t+1})} = \alpha \left(\frac{K_{t+1} / X_{t+1}}{n_{t+1}} \right)^{\alpha-1} + 1 - \delta & & + (1 - \rho) \left(\frac{bu_C(C_{t+1}, lfp_{t+1})}{u_C(C_t, lfp_t)} \right) \cdot \frac{\Omega_{t+1} (1 - m_s(s_{t+1}, v_{t+1}))}{m_v(s_{t+1}, v_{t+1})} \\
 (4) \quad & C_t + K_{t+1} - (1 - \delta)K_t + \Omega_t \cdot v_t = K_t^\alpha (n_t X_t)^{1-\alpha} & (5) \quad & n_t = (1 - \rho)n_{t-1} + m(s_t, v_t) & (6) \quad & X_{t+1} = \gamma_t X_t
 \end{aligned}$$

□ **(K2) All real (goods-denominated...) quantity variables grow at same rate in the extremely long run**

$$\begin{aligned}
 & \Rightarrow \frac{Y_{t+1}}{Y_t} = \frac{C_{t+1}}{C_t} = \frac{K_{t+1}}{K_t} = \frac{\Omega_{t+1}}{\Omega_t} = \frac{X_{t+1}}{X_t} = \gamma, \quad \forall t \\
 & \Rightarrow y_t \equiv \frac{Y_t}{X_t} = \bar{y}, \quad k_t \equiv \frac{K_t}{X_t} = \bar{k}, \quad c_t \equiv \frac{C_t}{X_t} = \bar{c}, \quad \omega_t \equiv \frac{\Omega_t}{X_t} = \bar{\omega} \quad \forall t
 \end{aligned}$$

RESTRICTIONS ON FUNCTIONAL FORMS

□ Deterministic dynamics of $(C_t, K_{t+1}, lfp_t, n_t, v_t, X_t)$ governed by

$$\begin{aligned}
 (1) \quad & -\frac{u_{lfp}(C_t, lfp_t)}{u_C(C_t, lfp_t)} = \Omega_t \cdot \frac{m_s(s_t, v_t)}{m_v(s_t, v_t)} & (3) \quad & \frac{\Omega_t}{m_v(s_t, v_t)} = (1-\alpha)X_t \left(\frac{K_t / X_t}{n_t} \right)^\alpha \text{ Recall } F(\cdot) \text{ is CRS} \\
 (2) \quad & \frac{u_C(C_t, lfp_t)}{bu_C(C_{t+1}, lfp_{t+1})} = \alpha \left(\frac{K_{t+1} / X_{t+1}}{n_{t+1}} \right)^{\alpha-1} + 1 - \delta & & + (1-\rho) \left(\frac{bu_C(C_{t+1}, lfp_{t+1})}{u_C(C_t, lfp_t)} \right) \cdot \frac{\Omega_{t+1} (1 - m_s(s_{t+1}, v_{t+1}))}{m_v(s_{t+1}, v_{t+1})} \\
 (4) \quad & C_t + K_{t+1} - (1-\delta)K_t + \Omega_t \cdot v_t = K_t^\alpha (n_t X_t)^{1-\alpha} & (5) \quad & n_t = (1-\rho)n_{t-1} + m(s_t, v_t) & (6) \quad & X_{t+1} = \gamma_t X_t
 \end{aligned}$$

□ Scale (1), (3), and (4) by X_t to write in stationary form

$$\begin{aligned}
 (1) \quad & -\frac{u_{lfp}(C_t, lfp_t)}{u_C(C_t, lfp_t)} = \omega_t \cdot \frac{m_s(s_t, v_t)}{m_v(s_t, v_t)} & (3) \quad & \frac{\omega_t}{m_v(s_t, v_t)} = (1-\alpha) \left(\frac{k_t}{n_t} \right)^\alpha \\
 (2) \quad & \frac{u_C(C_t, lfp_t)}{bu_C(C_{t+1}, lfp_{t+1})} = \alpha \left(\frac{k_{t+1}}{n_{t+1}} \right)^{\alpha-1} + 1 - \delta & & + \gamma_t \cdot (1-\rho) \left(\frac{bu_C(C_{t+1}, lfp_{t+1})}{u_C(C_t, lfp_t)} \right) \cdot \frac{\omega_{t+1} \cdot (1 - m_s(s_{t+1}, v_{t+1}))}{m_v(s_{t+1}, v_{t+1})} \\
 (4) \quad & c_t + \gamma_t k_{t+1} - (1-\delta)k_t + \omega \cdot v_t = k_t^\alpha n_t^{1-\alpha} & (5) \quad & n_t = (1-\rho)n_{t-1} + m(s_t, v_t) & (6) \quad & X_{t+1} = \gamma_t X_t
 \end{aligned}$$

RESTRICTIONS ON FUNCTIONAL FORMS

□ Deterministic dynamics of $(C_t, K_{t+1}, lfp_t, n_t, v_t, X_t)$ governed by

$$(1) \quad -\frac{u_{lfp}(C_t, lfp_t)}{u_C(C_t, lfp_t)} = \omega_t \cdot \frac{m_s(s_t, v_t)}{m_v(s_t, v_t)}$$

$$(3) \quad \frac{\omega_t}{m_v(s_t, v_t)} = (1 - \alpha) \left(\frac{\bar{k}}{n_t} \right)^\alpha$$

$$(2) \quad \frac{u_C(C_t, lfp_t)}{bu_C(C_{t+1}, lfp_{t+1})} = \alpha \left(\frac{\bar{k}}{n_{t+1}} \right)^{\alpha-1} + 1 - \delta$$

$$+ \gamma_t \cdot (1 - \rho) \left(\frac{bu_C(C_{t+1}, lfp_{t+1})}{u_C(C_t, lfp_t)} \right) \cdot \frac{\omega_{t+1} \cdot (1 - m_s(s_{t+1}, v_{t+1}))}{m_v(s_{t+1}, v_{t+1})}$$

$$(4) \quad \bar{c} + \gamma_t \bar{k} - (1 - \delta) \bar{k} + \omega \cdot v_t = \bar{k}^\alpha n_t^{1-\alpha}$$

$$(5) \quad n_t = (1 - \rho) n_{t-1} + m(s_t, v_t)$$

$$(6) \quad X_{t+1} = \gamma_t X_t$$

RESTRICTIONS ON FUNCTIONAL FORMS

□ Deterministic dynamics of $(C_t, K_{t+1}, lfp_t, n_t, v_t, X_t)$ governed by

$$(1) \quad -\frac{u_{lfp}(C_t, lfp_t)}{u_C(C_t, lfp_t)} = \omega_t \cdot \frac{m_s(s_t, v_t)}{m_v(s_t, v_t)}$$

$$(3) \quad \frac{\omega_t}{m_v(s_t, v_t)} = (1-\alpha) \left(\frac{\bar{k}}{n_t} \right)^\alpha$$

$$(2) \quad \frac{u_C(C_t, lfp_t)}{bu_C(C_{t+1}, lfp_{t+1})} = \alpha \left(\frac{\bar{k}}{n_{t+1}} \right)^{\alpha-1} + 1 - \delta$$

$$+ \gamma_t \cdot (1-\rho) \left(\frac{bu_C(C_{t+1}, lfp_{t+1})}{u_C(C_t, lfp_t)} \right) \cdot \frac{\omega_{t+1} \cdot (1 - m_s(s_{t+1}, v_{t+1}))}{m_v(s_{t+1}, v_{t+1})}$$

$$(4) \quad \bar{c} + \gamma_t \bar{k} - (1-\delta)\bar{k} + \omega \cdot v_t = \bar{k}^\alpha n_t^{1-\alpha}$$

$$(5) \quad n_t = (1-\rho)n_{t-1} + m(s_t, v_t)$$

$$(6) \quad X_{t+1} = \gamma_t X_t$$

□ (K4 – generalized) Time spent in each activity is stationary

$$\Rightarrow lfp_t = \bar{lfp}$$

$$\text{and } s_t = \bar{s}$$

$$\text{and } n_t = \bar{n}$$

along deterministic path.

BUT

lfp is endogenous...

s is endogenous...

n is endogenous...

□ Recall definition: $lfp_t = (1-\rho)n_{t-1} + s_t$

RESTRICTIONS ON FUNCTIONAL FORMS

□ **Deterministic dynamics of $(C_t, K_{t+1}, lfp_t, n_t, v_t, X_t)$ governed by**

$$(1) \quad -\frac{u_{lfp}(C_t, \bar{lfp})}{u_C(C_t, \bar{lfp})} = \omega \cdot \frac{m_s(\bar{s}, \bar{v})}{m_v(\bar{s}, \bar{v})} \quad (3) \quad \frac{\omega}{m_v(\bar{s}, \bar{v})} = (1-\alpha) \left(\frac{\bar{k}}{\bar{n}} \right)^\alpha$$

$$(2) \quad \frac{u_C(C_t, \bar{lfp})}{bu_C(C_{t+1}, \bar{lfp})} = \alpha \left(\frac{\bar{k}}{\bar{n}} \right)^{\alpha-1} + 1 - \delta \quad + \gamma_t \cdot (1-\rho) \left(\frac{bu_C(C_{t+1}, \bar{lfp})}{u_C(C_t, \bar{lfp})} \right) \cdot \frac{\omega \cdot (1-m_s(\bar{s}, \bar{v}))}{m_v(\bar{s}, \bar{v})}$$

$$(4) \quad \bar{c} + \gamma_t \bar{k} - (1-\delta)\bar{k} + \omega \cdot v_t = \bar{k}^\alpha n_t^{1-\alpha} \quad (5) \quad \bar{n} = (1-\rho)\bar{n} + m(\bar{s}, \bar{v}) \quad (6) \quad X_{t+1} = \gamma_t X_t$$

□ **Implied already (RHS of (2)) is**

□ **(K3) Real interest rate is stationary**

□ **Final step – functional form for utility?**

RESTRICTIONS ON FUNCTIONAL FORMS

□ Deterministic dynamics of $(C_t, K_{t+1}, lfp_t, n_t, v_t, X_t)$ governed by

$$(1) \quad -\frac{u_{lfp}(C_t, \bar{lfp})}{u_C(C_t, \bar{lfp})} = \omega \cdot \frac{m_s(\bar{s}, \bar{v})}{m_v(\bar{s}, \bar{v})} \quad (3) \quad \frac{\omega}{m_v(\bar{s}, \bar{v})} = (1-\alpha) \left(\frac{\bar{k}}{\bar{n}} \right)^\alpha$$

$$(2) \quad \frac{u_C(C_t, \bar{lfp})}{bu_C(C_{t+1}, \bar{lfp})} = \alpha \left(\frac{\bar{k}}{\bar{n}} \right)^{\alpha-1} + 1 - \delta + \gamma_t \cdot (1-\rho) \left(\frac{bu_C(C_{t+1}, \bar{lfp})}{u_C(C_t, \bar{lfp})} \right) \cdot \frac{\omega \cdot (1-m_s(\bar{s}, \bar{v}))}{m_v(\bar{s}, \bar{v})}$$

$$(4) \quad \bar{c} + \gamma_t \bar{k} - (1-\delta)\bar{k} + \omega \cdot v_t = \bar{k}^\alpha n_t^{1-\alpha} \quad (5) \quad \bar{n} = (1-\rho)\bar{n} + m(\bar{s}, \bar{v}) \quad (6) \quad X_{t+1} = \gamma_t X_t$$

□ Implied already (RHS of (2)) is

□ (K3) Real interest rate is stationary

□ Final step – functional form for utility?

□ Observations

□ Optimal choice of lfp must be independent of X_t (from (1))

□ Requires offsetting income and substitution effects of wages (long-run productivity) on LFP (aka, labor supply)

□ IMRS can only depend on C_{t+1}/C_t (from (2)), which in turn = γ_t

RESTRICTIONS ON FUNCTIONAL FORMS

□ **Deterministic dynamics of $(C_t, K_{t+1}, lfp_t, n_t, v_t, X_t)$ governed by**

$$(1) \quad -\frac{u_{lfp}(C_t, \bar{lfp})}{u_C(C_t, \bar{lfp})} = \omega \cdot \frac{m_s(\bar{s}, \bar{v})}{m_v(\bar{s}, \bar{v})} \quad (3) \quad \frac{\omega}{m_v(\bar{s}, \bar{v})} = (1-\alpha) \left(\frac{\bar{k}}{\bar{n}} \right)^\alpha$$

$$(2) \quad \frac{u_C(C_t, \bar{lfp})}{bu_C(C_{t+1}, \bar{lfp})} = \alpha \left(\frac{\bar{k}}{\bar{n}} \right)^{\alpha-1} + 1 - \delta + \gamma_t \cdot (1-\rho) \left(\frac{bu_C(C_{t+1}, \bar{lfp})}{u_C(C_t, \bar{lfp})} \right) \cdot \frac{\omega \cdot (1-m_s(\bar{s}, \bar{v}))}{m_v(\bar{s}, \bar{v})}$$

$$(4) \quad \bar{c} + \gamma_t \bar{k} - (1-\delta)\bar{k} + \omega \cdot v_t = \bar{k}^\alpha n_t^{1-\alpha} \quad (5) \quad \bar{n} = (1-\rho)\bar{n} + m(\bar{s}, \bar{v}) \quad (6) \quad X_{t+1} = \gamma_t X_t$$

□ **Implied already (RHS of (2)) is**

□ **(K3) Real interest rate is stationary**

□ **Final step – functional form for utility?**

□ **Two requirements together imply**

$$u(C_t, lfp_t) = \left\{ \begin{array}{ll} \frac{[C_t v(lfp_t)]^{1-\sigma} - 1}{1-\sigma} & \text{if } \sigma > 0, \sigma \neq 1 \\ \ln C_t + v(lfp_t) & \text{if } \sigma = 1 \end{array} \right\}$$